

# Course Outcomes (COs)

## Department of Mechanical Engineering

**Programme Name : M.Tech.-Industrial Automation and Robotics**

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## M Tech in Industrial Automation and Robotics

### Course Outcomes of First -Year Courses

<b>Course Name</b>	<b>Applied Mathematics</b>
<b>Course Code</b>	<b>22MAR11</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MAR11.1</b>	Apply matrix and iterative methods to solve a system of linear algebraic equations.
<b>22MAR11.2</b>	Apply geometry of Linear transformations and construct orthonormal basis of an inner product space
<b>22MAR11.3</b>	Diagonalising a matrix by finding the eigenvalues and the corresponding eigenvectors, compute the smallest and the largest eigenvalues and also singular values.
<b>22MAR11.4</b>	Use statistical tools to draw inferences for the given data

<b>Course Name</b>	<b>Computer Integrated Manufacturing</b>
<b>Course Code</b>	<b>22MAR12</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MAR12.1</b>	To impart the basic concepts in manufacturing systems and fundamentals of NC & CNC system
<b>22MAR12.2</b>	Knowledge enhancement in design consideration and increasing productivity with NC machine tools, machining centers and tooling for CNC machines
<b>22MAR12.3</b>	To enhance students' awareness in part programming and computer control in NC
<b>22MAR12.4</b>	To impart the basic concepts in Computerized Manufacturing Planning and Control Systems

<b>Course Name</b>	<b>Agile Manufacturing</b>
<b>Course Code</b>	<b>22MAR13</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MAR13.1</b>	Explain the conceptual frame work of agile manufacturing environment
<b>22MAR13.2</b>	Apply the concepts of enterprise design process to develop agile manufacturing
<b>22MAR13.3</b>	Apply interdisciplinary design concepts to the production functions
<b>22MAR13.4</b>	Apply the principles of agility for supply chain management

<b>Course Name</b>	<b>Drives and Control System in Automation</b>
<b>Course Code</b>	<b>22MIA14</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MIA14.1</b>	Describe and analyze working principles of various types of motors, differences, characteristics and selection criteria, control methods, SCADA
<b>22MIA14.2</b>	Apply the knowledge in selection of motors, heating effects and braking concepts in various industrial applications
<b>22MIA14.3</b>	Construct a program using PLC to problems pertaining to automation industries
<b>22MIA14.4</b>	To understand visualization systems and its integrations

<b>Course Name</b>	<b>Sensors Applications in Manufacturing</b>
<b>Course Code</b>	<b>22MIA15</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MIA15.1</b>	Explain various signal condition devices used in electronic devices and use of appropriate method in signal conditions in various applications.
<b>22MIA15.2</b>	Describe impact of an RFID system on manufacturing, defense, distribution, retail & health sectors & abstract (“filter”) information in RFID
<b>22MIA15.3</b>	Summarizes the future advances to the quality and integrity of manufacturing and related sectors resulting from the use of RFID and other sensor
<b>22MIA15.4</b>	Analyze and choose appropriate sensors in different industrial applications.

<b>Course Name</b>	<b>PLC and Sensors Laboratory</b>
<b>Course Code</b>	<b>22MIAL17</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MIAL17.1</b>	The students will be able to write and execute PLC ladder logic for different practical problems of automation
<b>22MIAL17.2</b>	Students will be able to analyze the suitability of different sensors for different operational requirements in automation
<b>22MIAL17.3</b>	Apply integration techniques of PLC ladder logic with sensor data by designing responsive automation systems.
<b>22MIAL17.4</b>	Diagnose and resolve issues in PLC-sensor systems, demonstrating proficiency in troubleshooting and maintaining automation setups.

<b>Course Name</b>	<b>Robotics for Industrial Automation</b>
<b>Course Code</b>	<b>22 MAR21</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MAR21.1</b>	Explain basic components, drive systems, control systems and configurations of industrial Robots.
<b>22MAR21.2</b>	Explain various sensing, vision and teaching techniques of robotics systems.
<b>22MAR21.3</b>	Apply different robot teaching methods and programming techniques for various industrial applications.
<b>22MAR21.4</b>	Apply analytical techniques and basic principles of robotic design for solving the kinematics of a robot manipulator.

<b>Course Name</b>	<b>Hydraulics and Pneumatics Control System</b>
<b>Course Code</b>	<b>22MIA22</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MIA22.1</b>	Study of working principle of various components used in hydraulic and pneumatic systems.
<b>22MIA22.2</b>	Select different components used in hydraulic and pneumatic systems.
<b>22MIA22.3</b>	Design of Hydraulic and Pneumatic circuits.
<b>22MIA22.4</b>	Understand industrial applications of hydraulic and pneumatic circuits.

<b>Course Name</b>	<b>MINI PROJECT WITH SEMINAR</b>
<b>Course Code</b>	<b>22MTE25</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MTE25.1</b>	Make links across different areas of knowledge and to generate, develop and evaluate ideas and information to apply these skills to the project task.
<b>22MTE25.2</b>	Habituated to critical thinking and use problem solving skills.
<b>22MTE25.3</b>	Communicate effectively and to present ideas clearly and coherently in both the written and oral forms.
<b>22MTE25.4</b>	Learn on their own, reflect on their learning and take appropriate actions to improve it.

<b>Course Name</b>	<b>Automation and Robotics Laboratory</b>
<b>Course Code</b>	<b>22MIAL26</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MIAL26.1</b>	Simulate manufacturing processes before being put to actual machining
<b>22MIAL26.2</b>	Apply/develop solutions or to do research in the areas of Design and simulation in Mechanical Engineering.
<b>22MIAL26.3</b>	Program and control robot path for industrial applications.
<b>22MIAL26.4</b>	Analyze advanced automation and robotics concepts, showcasing a deep understanding of their applications in complex engineering contexts.

## Course Outcomes of Second -Year Courses

<b>Course Name</b>	<b>Artificial Intelligence in expert system Automation</b>
<b>Course Code</b>	<b>22MAR31</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MAR31.1</b>	Understand problem solving methods, state space problems and search methods.
<b>22MAR31.2</b>	Understand knowledge acquisition and representation methods.
<b>22MAR31.3</b>	Assess critically the techniques presented and apply them to real world problems.
<b>22MAR31.4</b>	Develop knowledge of decision making and learning methods.

<b>Course Name</b>	<b>PROJECT WORK PHASE -2</b>
<b>Course Code</b>	<b>22MIA41</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>22MIA41.1</b>	Make links across different areas of knowledge and to generate, develop and evaluate ideas and information so as to apply these skills to the project task
<b>22MIA41.2</b>	Habituated to critical thinking and use problem solving skills
<b>22MIA41.3</b>	Communicate effectively and to present ideas clearly and coherently in both the written and oral forms
<b>22MIA41.4</b>	Learn on their own, reflect on their learning and take appropriate actions to improve it.

# Industrial Automation and Robotics- 2020 Scheme

## Course Outcomes of First-Year Courses

<b>Course Name</b>	<b>NUMERICAL METHODS FOR ENGINEERS</b>
<b>Course Code</b>	<b>20MCM11</b>
<b>Course outcomes (COs): At the end of the course the student will be able to:</b>	
<b>20MCM11.1</b>	Use the numerical methods for solving algebraic and transcendental equations which comes in mechanical engineering courses
<b>20MCM11.2</b>	Demonstrate common numerical methods and how they are used to obtain approximate solutions
<b>20MCM11.3</b>	Analyze and evaluate the accuracy of common numerical methods
<b>20MCM11.4</b>	Apply modern tools numerical methods to solve problems

<b>Course Name</b>	<b>MECHATRONICS AND APPLICATIONS</b>
<b>Course Code</b>	<b>20MCM12</b>
<b>Course outcomes (COs): At the end of the course the student will be able to:</b>	
<b>20MCM12.1</b>	Identify and explain the architectures of 8085 and 8086 microprocessors. Describe the concept of segmentation
<b>20MCM12.2</b>	Interfacing with respect to memory and I/O. Discuss the application examples of stepper motor.
<b>20MCM12.3</b>	Understand the concept of Microcontroller and microprocessor and PIC architectures and core concepts.
<b>20MCM12.4</b>	Discuss about various assembly programming mechanics and explain various instructions used for Microcontroller assembly programming



<b>Course Name</b>	<b>COMPUTER INTEGRATED MANUFACTURING SYSTEM</b>
<b>Course Code</b>	<b>20MCM13</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM13.1</b>	Apply the concepts of machining for the purpose of selection of appropriate machining centers, machining parameters.
<b>20MCM13.2</b>	Create and demonstrate the technical documentation for design/ selection of suitable drive technologies, precision components and an overall CNC machine tool system for automation of machining operations
<b>20MCM13.3</b>	Create and validate NC part program data using manual data input (MDI) and automatically using standard commercial CAM package for manufacturing of required component.
<b>20MCM13.4</b>	Design automated material handling and storage systems for a typical production system and control the process

<b>Course Name</b>	<b>CONTROL SYSTEM ENGINEERING</b>
<b>Course Code</b>	<b>20MCM14</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM14.1</b>	Categorize different types of system and identify a set of algebraic equations to represent and model a complicated system into a more simplified form.
<b>20MCM14.2</b>	Characterize any system in Laplace domain to illustrate different specification of the system using transfer function concept
<b>20MCM14.3</b>	Employ time domain analysis to predict and diagnose transient performance parameters of the system for standard input functions and determine the (absolute) stability of a closed-loop control system.
<b>20MCM14.4</b>	Formulate different types of analysis in frequency domain to explain the nature of stability of the system

<b>Course Name</b>	<b>OPERATION MANAGEMENT</b>
<b>Course Code</b>	<b>20MCM15</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM15.1</b>	Identify the elements of operations management and various transformation processes to enhance productivity and competitiveness.
<b>20MCM15.2</b>	Identify the roles and responsibilities of operations managers in different organizational contexts
<b>20MCM15.3</b>	Apply and analyze and evaluate various Linear & Dynamic programming models to various real time problems
<b>20MCM15.4</b>	Solve and analyze problems using different forecasting techniques and develop aggregate capacity plans in different operation environments.

<b>Course Name</b>	<b>CIM LABORATORY</b>
<b>Course Code</b>	<b>20MCML16</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCML16.1</b>	Simulate manufacturing processes before being put to actual machining
<b>20MCML16.2</b>	Apply/develop solutions or to do research in the areas of Design and simulation in Mechanical Engineering
<b>20MCML16.3</b>	Developing and applying computer software and hardware to mechanical design and manufacturing fields
<b>20MCML16.4</b>	Formulate relevant research problems; conduct experimental and/or analytical study and analyzing results with modern mathematical / scientific methods and use of software tools.

<b>Course Name</b>	<b>DESIGN OF ROBOTIC SYSTEMS</b>
<b>Course Code</b>	<b>20MCM21</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM21.1</b>	Demonstrate the relationship between mechanical structures of industrial robots and their operational workspace characteristics.
<b>20MCM21.2</b>	Apply the concepts of coordinate transformations for development of arm equation and subsequently the inverse kinematics model for given serial manipulator.
<b>20MCM21.3</b>	Develop and analyze the mathematical model for trajectory planning, resolved motion rate control and dynamics model for a given serial robotic manipulator
<b>20MCM21.4</b>	Develop the algorithms for design of robotic work cell controller and its programming.

<b>Course Name</b>	<b>PROGRAMMABLE LOGIC CONTROLLER</b>
<b>Course Code</b>	<b>20MCM22</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM22.1</b>	Describe and analyze working principles of various types of motors, differences, characteristics and selection criteria, control methods, SCADA.
<b>20MCM22.2</b>	Apply the knowledge in selection of motors, heating effects and braking concepts in various industrial applications.
<b>20MCM22.3</b>	Construct a program using PLC to problems pertaining to automation industries.
<b>20MCM22.4</b>	Demonstrate self-learning capability

<b>Course Name</b>	<b>PNEUMATIC AND HYDRAULIC CONTROL</b>
<b>Course Code</b>	<b>20MCM23</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM23.1</b>	Correlate the basics of hydraulics to the performance of fluid power systems.
<b>20MCM23.2</b>	Describe the working principle of hydraulic systems including pumps and controllers.
<b>20MCM23.3</b>	Correlate the basics of pneumatics to the performance of pneumatic systems.
<b>20MCM23.4</b>	Design and analyse problems relating to Pneumatic and Hydraulic control systems and components.

<b>Course Name</b>	<b>ROBOTICS AND AUTOMATION LABORATORY</b>
<b>Course Code</b>	<b>20MCML26</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCML26.1</b>	Write part programs for NC machining
<b>20MCML26.2</b>	Program and control robot path for industrial applications.
<b>20MCML26.3</b>	Simulate manufacturing processes before being put to actual machining
<b>20MCML26.4</b>	Evaluate and synthesize advanced concepts in automation and robotics, demonstrating a comprehensive understanding of their applications.

## Course outcomes of second year

<b>Course Name</b>	<b>ARTIFICIAL INTELLIGENCE AND EXPERT SYSTEM IN AUTOMATION</b>
<b>Course Code</b>	<b>20MCM31</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM31.1</b>	Understand problem solving methods, state space problems and search methods.
<b>20MCM31.2</b>	Understand knowledge acquisition and representation methods.
<b>20MCM31.3</b>	Assess critically the techniques presented and apply them to real world problems.
<b>20MCM31.4</b>	Develop knowledge of decision making and learning methods.

<b>Course Name</b>	<b>PROJECT WORK PHASE – 1</b>
<b>Course Code</b>	<b>20MCM34</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM34.1</b>	Demonstrate a sound technical knowledge of their selected project topic.
<b>20MCM34.2</b>	Undertake problem identification, formulation, and solution.
<b>20MCM34.3</b>	Design engineering solutions to complex problems utilizing a systems approach.
<b>20MCM34.4</b>	Demonstrate the knowledge, skills and attitudes of a professional engineer.

<b>Course Name</b>	<b>MINI PROJECT</b>
<b>Course Code</b>	<b>20MCM35</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM35.2</b>	Habituated to critical thinking and use problem solving skills.
<b>20MCM35.3</b>	Communicate effectively and to present ideas clearly and coherently in both the written and oral forms.
<b>20MCM35.4</b>	Learn on their own, reflect on their learning and take appropriate actions to improve it.
<b>20MCM35.2</b>	Habituated to critical thinking and use problem solving skills.

<b>Course Name</b>	<b>INTERNSHIP / PROFESSIONAL PRACTICE</b>
<b>Course Code</b>	<b>20MCM36</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM36.1</b>	Gain practical experience within industry in which the internship is done
<b>20MCM36.2</b>	Acquire knowledge of the industry in which the internship is done.
<b>20MCM36.3</b>	Develop a greater understanding about career options while more clearly defining personal career goals.
<b>20MCM36.4</b>	Develop and refine oral and written communication skills.

<b>Course Name</b>	<b>PROJECT WORK PHASE -2</b>
<b>Course Code</b>	<b>20MCM41</b>
Course outcomes (COs): At the end of the course the student will be able to:	
<b>20MCM41.1</b>	Make links across different areas of knowledge and to generate, develop and evaluate ideas and information so as to apply these skills to the project task.
<b>20MCM41.2</b>	Habituated to critical thinking and use problem solving skills
<b>20MCM41.3</b>	Communicate effectively and to present ideas clearly and coherently in both the written and oral forms.
<b>20MCM41.4</b>	Learn on their own, reflect on their learning and take appropriate actions to improve it.